



Efficient impulse noise detection method with ANFIS for accurate image restoration

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ABSTRACT

This paper proposes a novel adaptive neuro-fuzzy inference system (ANFIS) based impulse detection method for the restoration of images corrupted by impulse noise (IN). After the corrupted pixels detected by proposed detector, the Median filtering is performed for only these pixels. The performance of the proposed neuro-fuzzy detector based median filter (NFDMF) is evaluated on different test images and compared with 14 different comparison filters from the literature. Experimental results show that the proposed filter shows better performance than the comparison filters in the cases of being effective in noise suppression and detail preservation, especially when the noise ratio is very high.

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1. Introduction

Images are often corrupted by impulse noise (IN) due to errors generated in noisy sensors or communication channels. IN could degrade the image quality and cause great loss of image details. So it is important effectively to reduce noise from the image to facilitate subsequent image processing operations, such as edge detection, image segmentation, and object recognition. The goal of noise removal is to suppress the noise while preserving image details. To this end, a large number of algorithms [1–28] have been proposed to remove IN.

The median filter is one of the most popular nonlinear filters for removing IN because of its good denoising power [1] and computational efficiency [2]. Median filter utilize the rank order information of the pixels contained in the filtering window. It attempts to remove impulse noise by changing the luminance value of the each pixel in the image by the median value in its neighborhood. However, when the noise level is over 50%, some details and edges of the original image are smeared by the filter [3]. In order to overcome this drawback, different remedies of the median filter have been proposed. In [4] center weighted median filter (CWM) giving more weight only to the center value in the filtering window was presented. A nonlinear filter called tri-state median filter (TSM) combining the standard median filter with the CWM filter was proposed in [5] for suppressing impulse noise. The nonlinear LUM (low–upper–middle) smoothers, which are a subclass of LUM filters [6–8] that take advantage of the computational efficiency of order-statistics based operators, have

been shown to be equivalent to the CWM. Methods mentioned above can achieve good results at low noise density, but their denoising performances are unsatisfactory at high noise density. These methods are implemented uniformly across the image and thus tend to modify both noisy and noise-free pixels. Consequently, the effective removal of IN is often accomplished at the expense of blurred and distorted features, thus removing fine details in the image.

To avoid the damage of good pixels, the switching strategy is introduced by some recently published papers [9–14]. The switching scheme consists of the following two parts: the first part is an impulse detector which determines whether a target pixel is contaminated and the second part is a noise reduction filter which modifies only the pixels determined to be IN by the first part. In order to achieve accurate image restoration with the switching scheme, an accurate impulse detector is required, because the impulse detection result is utilized for the noise reduction filter.

Over the last few years, artificial intelligence-based nonlinear techniques such as neural networks and fuzzy systems have been attractive alternatives to classical noise detection and reduction techniques [15–28]. In [16] iterative fuzzy control-based filtering (IFCF) method was presented. The IFCF filter was designed for the removal of both impulse noise and Gaussian noise. This filtering approach is mainly based on the idea of not letting each point in the area of concern being uniformly fired by each of the basic fuzzy rules. The extended iterative fuzzy control-based filter (EIFCF) and the modified iterative fuzzy control-based filter (MIFCF) were also presented in [16]. EIFCF, which is a slightly modified version of the IFCF, was designed to counter the blurring of the image. In IFCF, the image gets more blurred after each iteration. MIFCF was designed to avoid this drawback. Smoothing

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Table 5
Runtimes of the mentioned methods for the *Baboon* image for different IN levels.

Method	Runtime (s)	
	% 10	% 80
CWM	9.2	8.7
TSM	18.1	18.0
LUM	3.6	3.2
FSB	165.9	166.4
IFCF	783.0	850.2
MIFCF	833.7	809.8
EIFCF	919.6	906.2
SFCF	323.6	317.9
FIRE	277.2	274.1
PWLFIRE	22.8	22.3
FMF	2.0	2.12
AWFM	143.9	144.6
ATMAV	24.9	24.6
NNDMF	2.56	2.58
NFDMF	0.6	3.1

4. Simulation results

The performance of the proposed method is tested under various noise conditions and on several popular images from the literature including *Lena*, *Baboon*, *Boats*, and *Peppers*. These images, which are 8-bit gray level images having the same size of 512×512 pixels, are shown in Fig. 4. The test images used in the experiments are generated by contaminating the original images by IN with an appropriate noise ratios ranging from 10% to 80% with an increment step of 10%.

For comparison, the corrupted test images are also filtered by using several conventional and state-of-the-art IN removal operators including CWM [4], TSM [5], LUM [6], FSB [15] (fuzzy similarity filter), IFCF [16], MIFCF [16], EIFCF [16], SFCF [17], FIRE [18], PWLFIRE [19], FMF [20,21] (fuzzy median filter), AWFM [22,23], and ATMAV [24]. In order to show performance of the ANFIS with respect to the neural network [31], the NFDMF results are also compared with the neural network detector median filter (NNDMF) results. The multilayer perceptron (MLP) network architecture was used in NNDMF. In MLP, the most suitable network configuration was two hidden layer with three neurons. In order to train MLP, the Levenberg–Marquardt learning algorithm [32] was used.

Restoration performances are quantitatively measured by the peak signal-to-noise ratio (PSNR) which is defined as

$$PSNR = 10 \log_{10} \left(\frac{255^2}{MSE} \right) \text{dB} \quad (11)$$

where mean-squared-error (MSE) is defined as

$$MSE = \frac{1}{MN} \sum_{i=1}^M \sum_{j=1}^N [org(i,j) - img(i,j)]^2 \quad (12)$$

where *org* is the original image, *img* is the filtered image of size *MN*. In addition, the mean absolute error (MAE) has also been taken as a quantitative measure to evaluate the levels of the edges and the details preserved, which is defined as

$$MAE = \frac{1}{MN} \sum_{i=1}^M \sum_{j=1}^N |org(i,j) - img(i,j)| \quad (13)$$

The restoration results for the *Lena* and *Baboon* test images corrupted with 70% IN are illustrated in Figs. 5 and 6, respectively. It is clearly seen from these figures that the proposed filter preserves edge sharpness and reduces many artifacts, even if the noise density is high. The PSNR values of the filters have also been

given in Tables 1 and 2 for making quantitative evaluation for *Lena* and *Baboon* test images. It is clearly seen from Tables 1 and 2 that the proposed NFDMF generates the best PSNR values. The MAE values for *Boats* and *Peppers* test images have been given in Tables 3 and 4. It is clear from Tables 3 and 4 that the proposed NFDMF shows better performance than other filters in the sense of being effective in noise suppression and detail preservation, especially when the noise density is very high.

Another important requirement of the modern image enhancement filters is robustness. Tables 1–4 indicate that the proposed NFDMF provides robustness substantially across a wide variation of noise ratios.

In order to evaluate the computational complexities, the runtimes of all the mentioned filters for *Baboon* image for different IN levels were determined and given in Table 5. The runtime analysis of the proposed NFDMF and concerned filters were conducted for test images using a Pentium IV, 3 GHz PC. It is seen from Table 5 that NFDMF is one of the fastest algorithms.

5. Conclusion

In this paper, an IN detector based on ANFIS is proposed. It can be seen from Figs. 5 and 6 that proposed NFDMF gives absolutely better restoration results in the restored images when compared with the IN suppression filters mentioned in this paper.

The advantages of the proposed filter may be summarized as follows.

1. The implementation of the method is very easy. It is based on a simple 2-input 1-output NF system.
2. The internal parameters of the NF system are determined by training. Training of the system can easily be realized by using artificial images generated in computer.
3. The NFDMF supplies superior restoration results compared to both median based filters (CWM, TSM, and LUM) and recently introduced fuzzy based filters (FSB, IFCF, MIFCF, EIFCF, SFCF, FIRE, PWLFIRE, FMF, AWFM, and ATMAV). The NFDMF is also better than the NNDMF.
4. The runtime of the proposed filter is less than most of the comparison filters. Finally, proposed method is easy to implement and has a very low execution time.

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